



### Non-Invasive Cognitive Workload Assessment in Robotic Teleoperated Surgery Using Eye-Tracking

Candidate: Alice Carcone

Advisor: **Prof. Elena De Momi** Co-Advisor: **Alberto Rota, Stefano Pomati** 

Master of Science in Biomedical Engineering – Ingegneria Biomedica April 3<sup>rd</sup> 2025

Academic Year 2023-2024

## **Clinical Context**

 $\bigcirc$ 

Robotic Surgery

increased precision

increased technique and interface complexity





Workload Monitoring

Prevents cognitive overload Varying data interpretation



### NEOF

[1] Yurko et al. (2010) [2] Blikkendaal et al. (2017)

**METHODOLOGY** 

# State of the Art



Traditional methods <sup>[3]</sup>

subjective not real-time disrupt surgical workflow





NEOF

Physiological parameters monitoring <sup>[4]</sup>

[3] Elek et al. (2021)

[4] Cao et al. (2022)

invasive





**O**BJECTIVE

METHODOLOGY

## State of the Art



Eye-Tracking derived parameters <sup>[5]</sup>

objective continuous real-time not invasive





Set of infrared emitter-receiver pairs



Frontal Emitter: detects center of pupil



NEOF

Lateral Emitters: detect corneal reflection



Output vector determines gaze direction







5

# **Open Issues and Objectives**

#### **Open Issues:**



Not established **non-invasive method** to monitor surgeons' workload



No clear strategy on **how to apply workload estimation** to optimize surgical performance and decision-making



No defined **threshold** to classify high vs. low workload

#### **Objectives:**



Leverage eye-tracking data to derive an **objective workload metric** 



**Validate the tool** by correlating workload with surgeons' subjective phase difficulty ratings



Analyze **workload variations** and establish trends across different surgical phases.

Aim:

Develop a post-operative non-invasive eye-tracking-based tool for cognitive workload estimation during robotic-assisted surgery.



**C**ONCLUSIONS

6

### **Workload Metric Construction Pipeline**





### Preprocessing



Preprocessing

NEOF

- 1. Invalid value handling
- 2. Gap interpolation ( < 75 ms)
- 3. Median filter
- 4. Transformation from tracker's reference system {T} a to the global one {G}:

 $p_G = R_x(\alpha) \cdot p_T$ 

5. Computation of visual angles:

$$\theta = \arctan\left(\frac{P_x - O_x}{|P_z - O_z|}\right) \cdot \frac{180}{\pi}$$
$$\phi = \arctan\left(\frac{P_y - O_y}{|P_z - O_z|}\right) \cdot \frac{180}{\pi}$$



 $p_G$  = gaze point in {G}  $p_T$  = gaze point in {T}  $R_x(\alpha)$  = rotation matrix  $\alpha$  = rotation angle  $P_x, P_y, P_z$  = coordinates of gaze endpoint  $\boldsymbol{O}_x, \boldsymbol{O}_y, \boldsymbol{O}_z$  = coordinates of gaze starting point  $\boldsymbol{\theta}$  = horizontal gaze angle  $\boldsymbol{\phi}$  = vertical gaze angle

### **Metrics Extraction**

**Pupil diameter** 

Blinks count

Gaze entropy

Fixation count

Saccades count Fixation duration

procedure

**Metrics Extraction** 

10s, 30s, 1min,

2min time

windows



1. Mean pupil diameter

$$P_w = \frac{P_{r,w} + P_{l,w}}{2}$$

w = window of length 10s/30s/1min/2min  $P_w$  = overall pupil diameter in w  $P_{r,w}$  = average pupil diameter of right eye in w $P_{l,w}$  = average pupil diameter of left eye in w





[75, 400]*ms* = range of blinks duration <sup>[6]</sup>

### **Metrics Extraction**





**Metrics Extraction** 

NEOF

↔ 50 ms

← 50 ms

1 min

 $P_{w}$ 

 $\boldsymbol{B}_{\boldsymbol{W}}$ 

 $H_{w}$ 

3.

w = window of length 10s/30s/1min/2min

n = number of cells of the field of view

 $p_i$  = probability of gaze occurring in the i-th cell

 $H_w$  = total gaze entropy in w

# **Metrics Extraction**



**Metrics Extraction** 

neor



Spatial probability distribution of the gaze on the screen

ncor

**O**BJECTIVE

METHODOLOGY

8

## **Metrics Extraction**



NEOF

**O**BJECTIVE

## **Metrics Extraction**



**OBJECTIVE** 

### **Metrics Extraction**



**Metrics Extraction** 

NEOF

 $T_w$  = is the mean fixation duration within w $t_f$  = duration of fixation f

## **Workload Computation**



**Workload Computation** 

POLITECNICO MILANO 1863

the six metrics corresponding to window w

9



## **Workload Validation Pipeline**





NEOF

## **Data Collection**



## **Subjective Difficulty Annotation**

Subjective Difficulty Annotation

- 1. Subdivision of procedures into **phases**
- 2. Computation of **mean difficulty scores** (scale 1-10)
- 3. Computation of weighted difficulty

 $D_w = \sum_{p=1}^9 \left( \frac{t_{p,w}}{t_w} \cdot d_p \right)$ 

Phase	Difficulty
Access intraperitoneal space	2.8
Mobilize and isolate cystic duct	4.8
Mobilize and isolate cystic artery	4.8
Ligate cystic duct	3.4
Ligate cystic artery Dissect gallbladder	3.6 4.4
Irrigate and inspect liver bed	3.2
Remove gallbladder	3.2
Remove trocars	2





NGOE

**O**BJECTIVE

METHODOLOGY

RESULTS

13

## Validation and Results





#### Validation of the Method



**Critical Analysis and Limitations** 



#### Possible solutions

- Moderate and valid correlation between objective cognitive load and surgeons' subjective assessments
- **Stability** across different time windows, with no significant impact on results.
- Results are statistically more reliable in **longer procedures**
- Imbalanced surgical phases distribution
- Qualitative difficulty imputation **not validated** in literature
- Refinement of the **raw data collection** process
- Data balancing techniques for machine learning to address dataset imbalance



# Conclusions

#### **Addressing Open Issues**

Eye-tracking offers a promising **non-invasive** and **objective** way to assess surgeon workload

A **validated** workload metric can enhance decision-making and performance

Defining a **universal threshold** remains an open challenge

#### **Future Developments**

**Combine** eye-tracking with other non-invasive physiological signals

- real-time **alert systems** for cognitive overload
- adaptive robotic assistance based on workload fluctuations
- personalized training programs

Develop a more **systematic** method for selfreported workload ratings





Thank you